



Gas Source Tracing With a Mobile Robot Using an Adapted Moth Strategy

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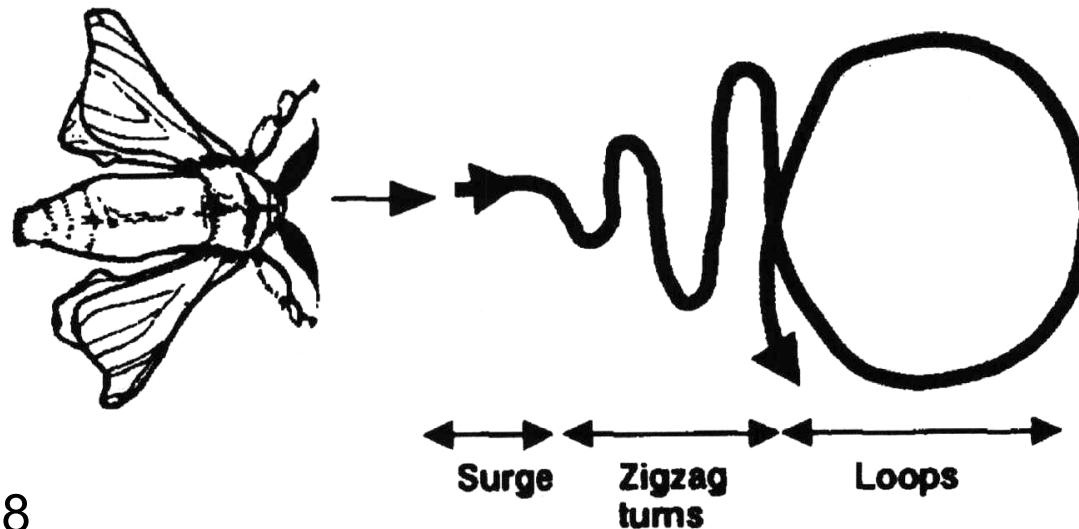


- 1) Gas Source Tracing Strategy of *Bombyx mori*
- 2) Gas-Sensitive Robot
- 3) Adapted Gas Source Tracing Strategy
- 4) Experimental Setup
- 5) Results
- 6) Summary & Outlook

1 Gas Source Tracing of *Bombyx mori*

■ Fixed Movement Pattern

- triggered by increased pheromone concentrations
- surge towards **upwind direction**

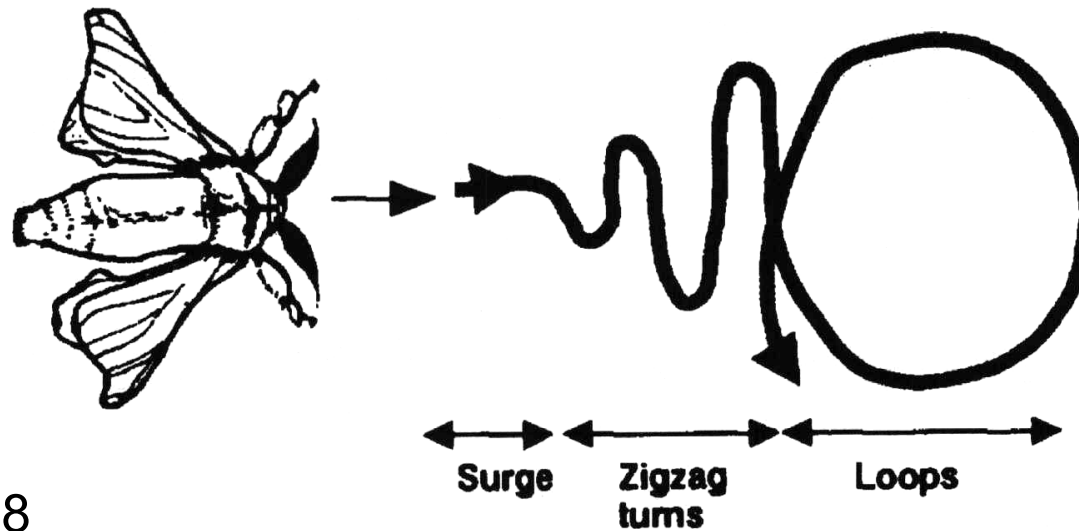


Kanzaki 1998

1 Gas Source Tracing of *Bombyx mori*

■ Fixed Movement Pattern

- implement a **local search** for the next patch

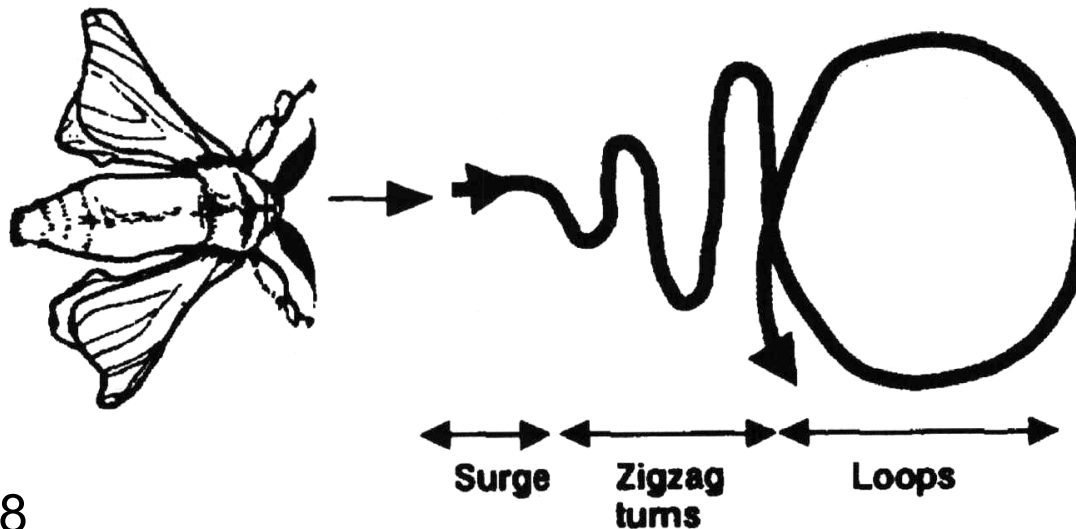


Kanzaki 1998

1

Gas Source Tracing of *Bombyx mori*

- *“Remarkably, the movement tracks that many species produce when tracking odour plumes have a very similar side-to-side zigzag shape whether walking, swimming, or flying.”* [Mark Willis]



Kanzaki 1998

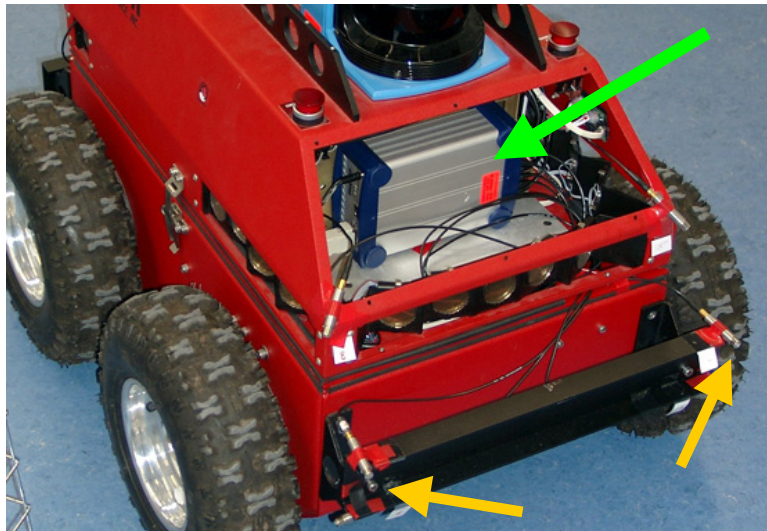
2 Experimental Setup - RoboMoth

- “Arthur” (ATRV-Jr.)
 - footprint = 80 x 65 cm
 - height = 55 cm
- Sensors Used
 - odometry
 - laser range scanner



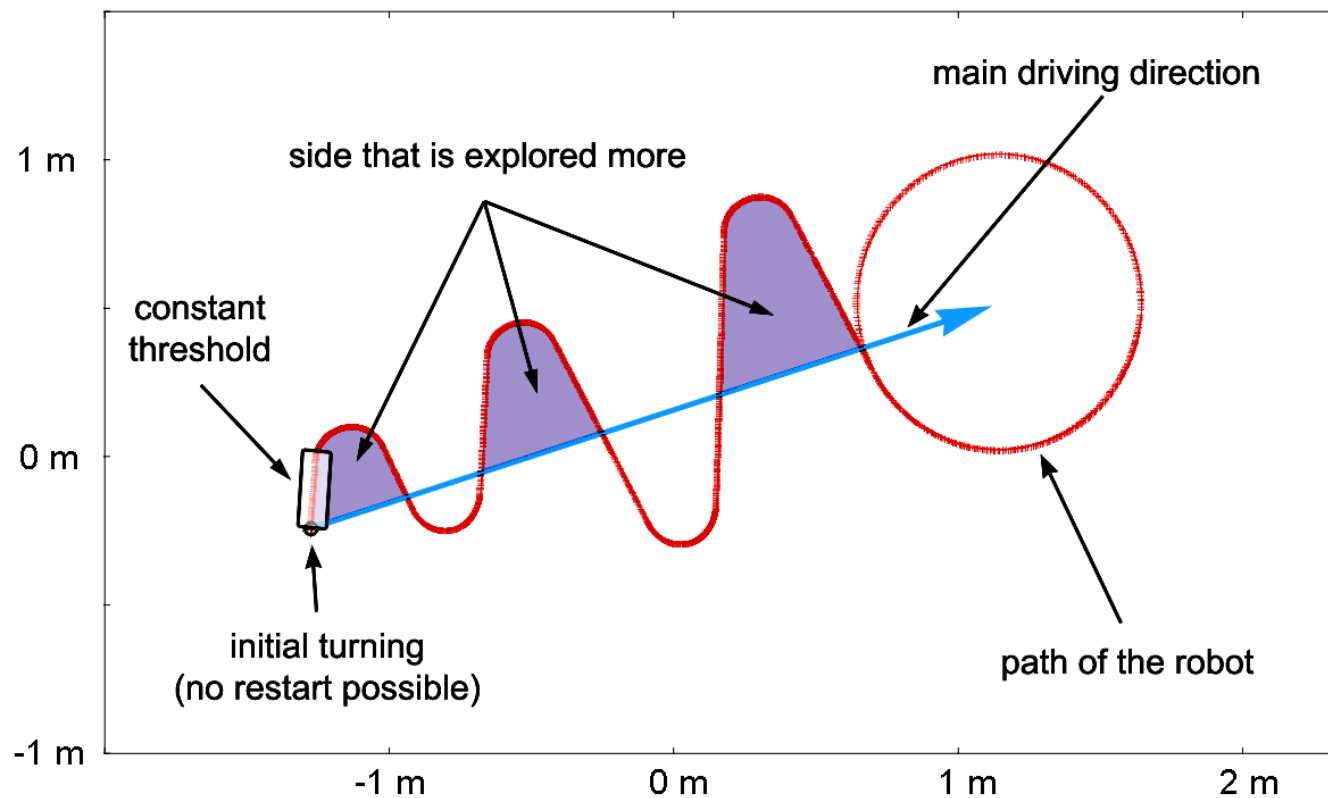
2 Experimental Setup - RoboMoth

- Gas Sensitive System
 - based on VOC-Vario
 - using two TGS 2620



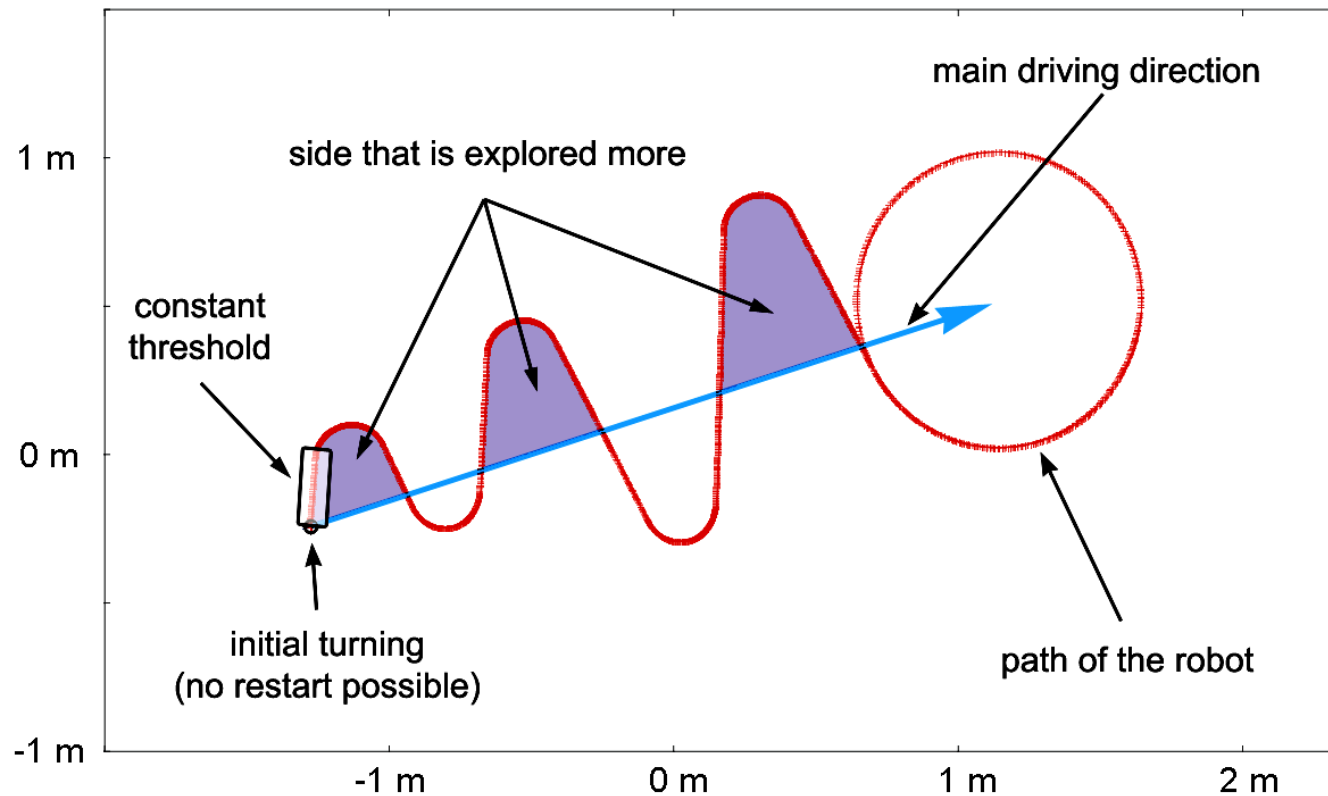
3 Adapted Gas Source Tracing Strategy

- Wind Direction not Known
- Exploit Relative Sensor Response



3 Adapted Gas Source Tracing Strategy

- Adapt Threshold
(Compensate Slow Response/Recovery)



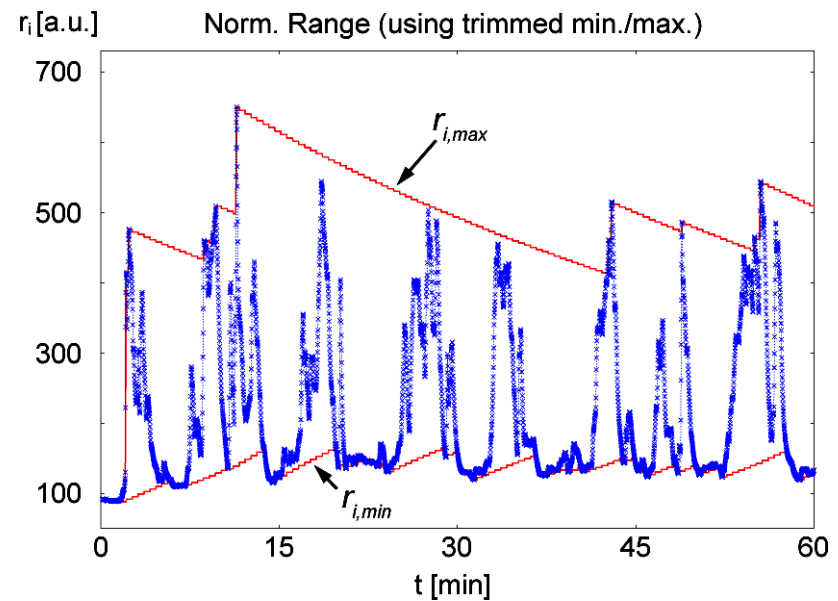
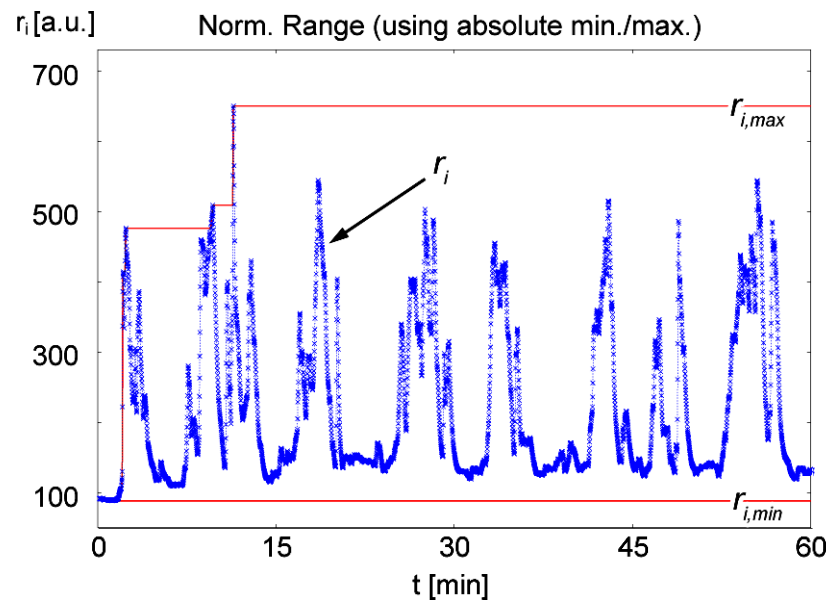
3 Data Preprocessing

- How to Calculate x ?
 - differences between individual sensors
 - different environmental conditions
 - increasing base level of concentration

$$x_t = \frac{R_t - R_{\min, t}}{R_{\max, t} - R_{\min, t}}$$

3 Data Preprocessing

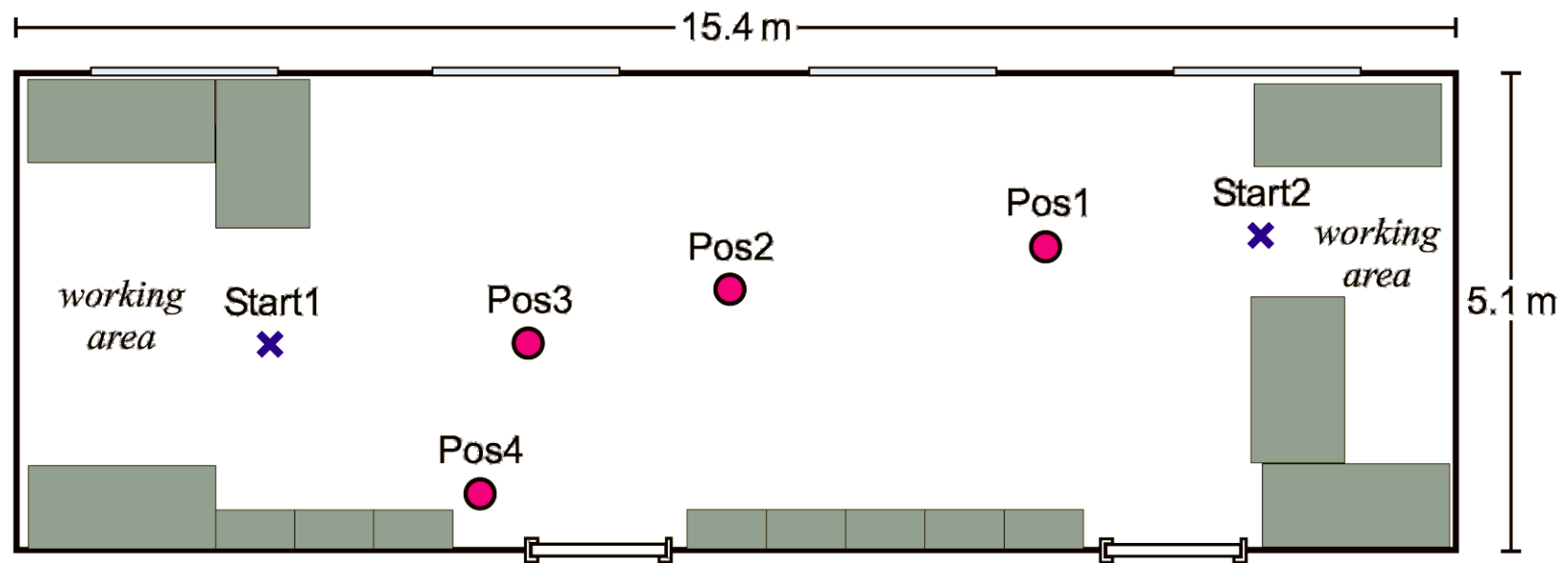
- Update Minimum and Maximum Dynamically
 - trimming by 1% every 30 s



4 Experimental Setup - Environment

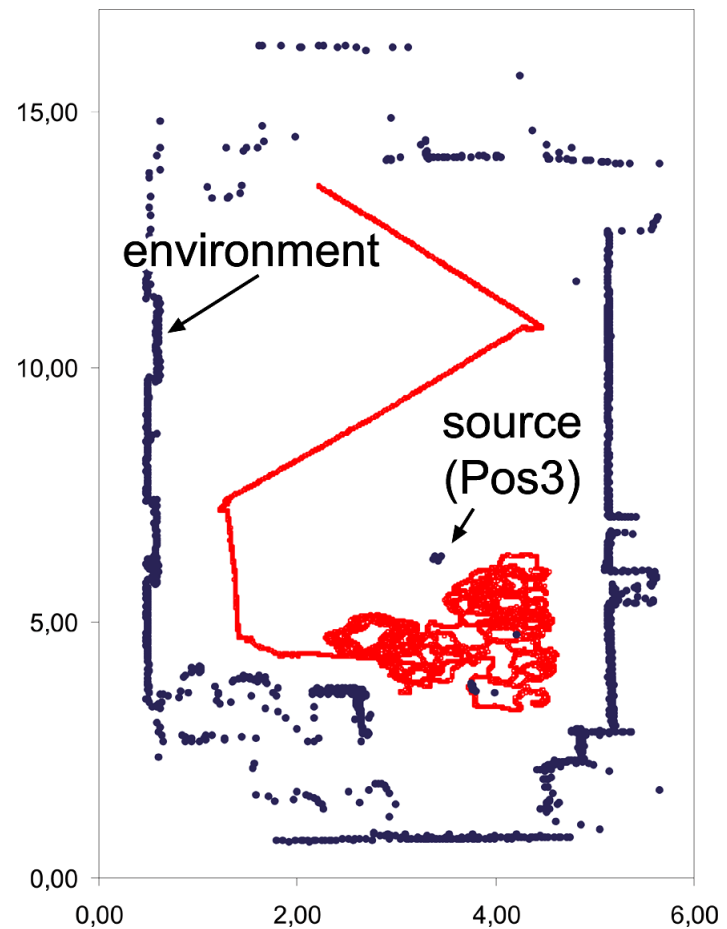
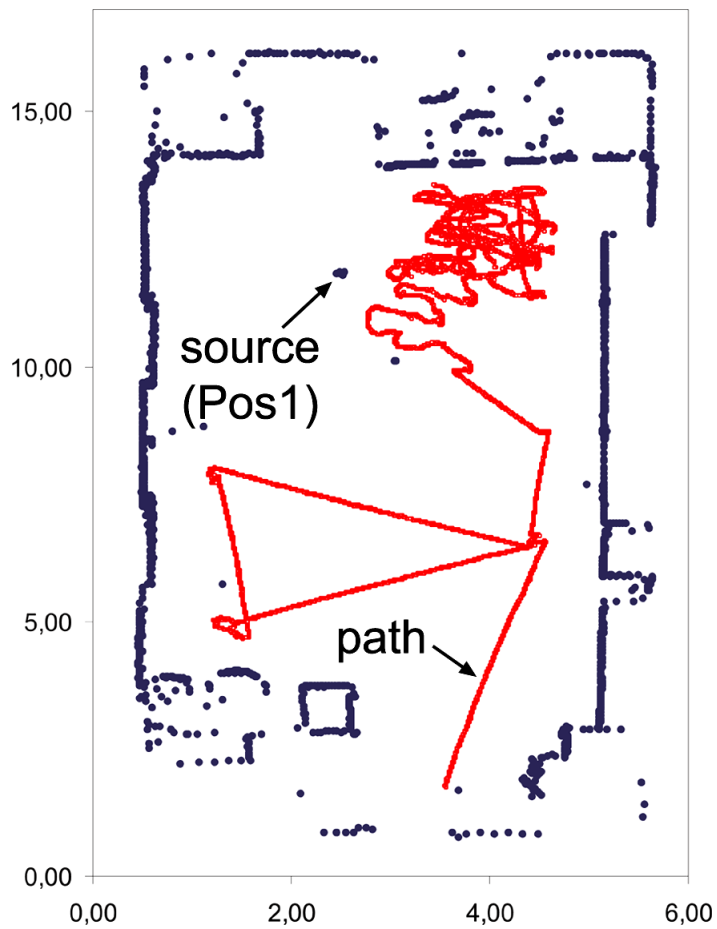
Office Environment

- natural indoor environment (to some extent)



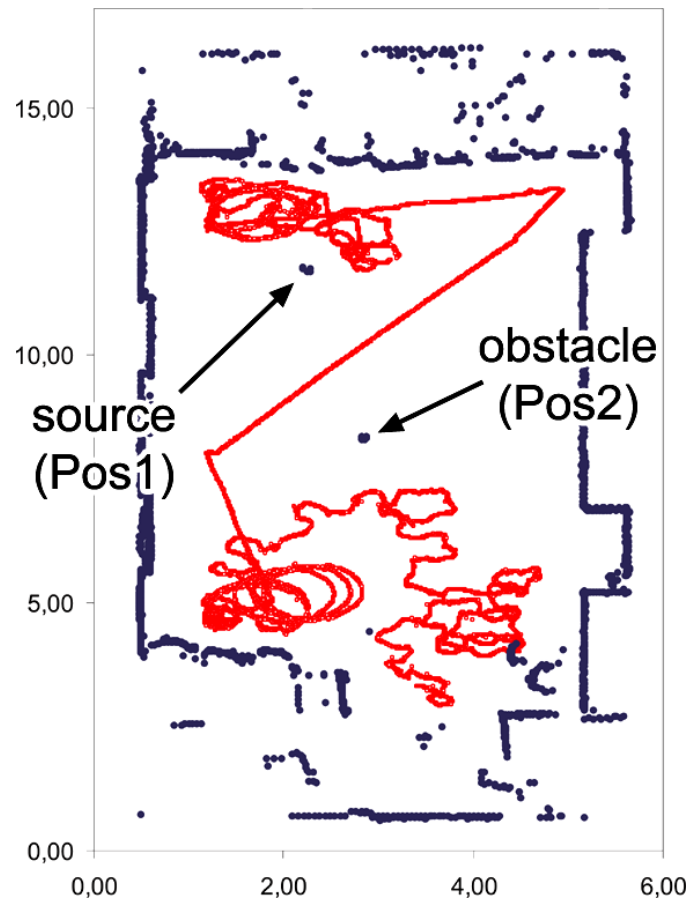
5 Results

Active Source Present



5 Results

■ Active Source Present



5 Results

■ No Active Source Present



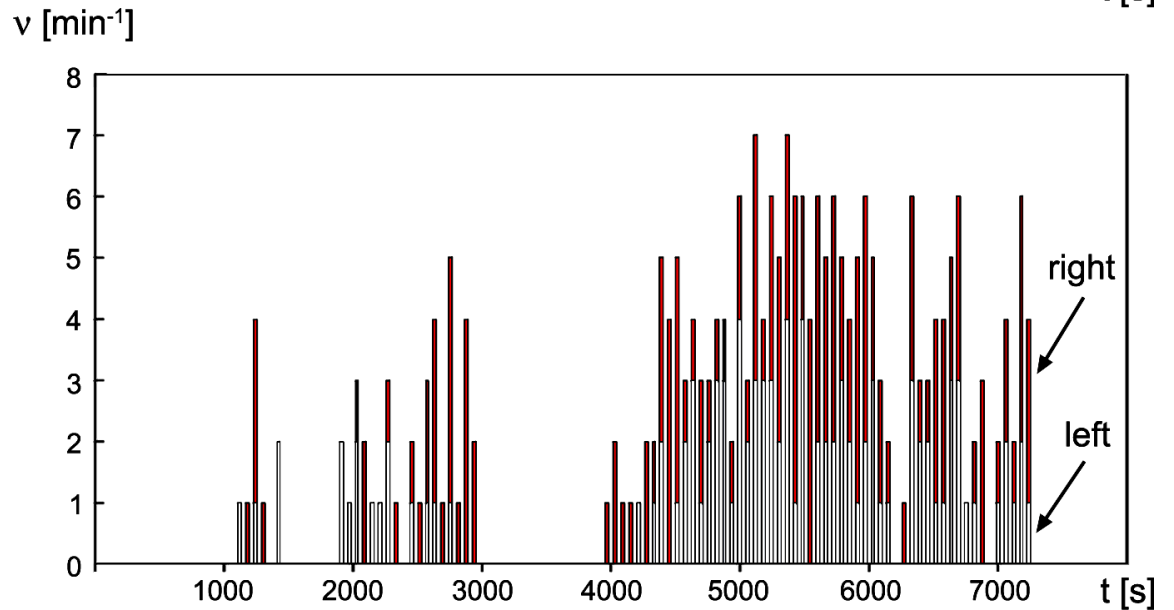
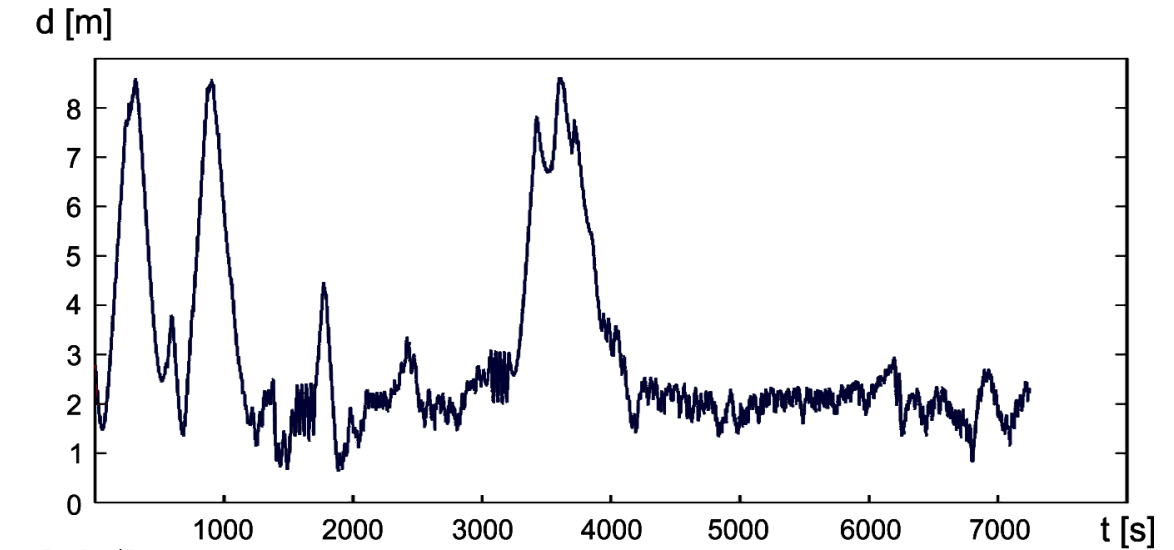
5 Results

■ Statistics (595 min)

	average distance	median distance
active source, all	(225.6 ± 179.6) cm	266.2 cm
inactive source	(317.7 ± 235.2) cm	336.8 cm

5 Results

- Statistics
 - after 1. trigger



5 Results

■ Statistics (595 min)

	average distance	median distance
active source, all	(225.6 ± 179.6) cm	266.2 cm
active source, after first trigger	(195.5 ± 119.8) cm	170.9 cm
inactive source	(317.7 ± 235.2) cm	336.8 cm

5 Results

■ Statistics (595 min)

	average distance	median distance
active source, all	(225.6 ± 179.6) cm	$p_{H_0} = 0.433$
active source, after first trigger	(195.5 ± 119.8) cm	$p_{H_0} = 0.173$
inactive source	(317.7 ± 235.2) cm	

5 Results

■ Statistics (595 min)

	average distance	median distance
active source, all	$p_{H_0} = 0.167$	266.2 cm
active source, after first trigger	$p_{H_0} = 0.167$	170.9 cm
inactive source		336.8 cm

6 Summary & Outlook

- Adapted Biomimetic Strategy (*Bombyx mori*)
 - local search (fixed motion pattern)
 - triggering mechanism
- Suitability for Indoor Gas Source Tracing
 - good evidence
- More Experiments needed
- Larger Environment



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Thank you!

